

Gianluca Rizzello

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RESEARCH INTEREST

Motion Control Systems

Development of motion, force, and interaction control algorithms for innovative mechatronic systems (high-speed electric motors, innovative fluidic actuators for robotics)

Smart Material Systems

Modeling, control, and self-sensing of innovative mechatronic actuator/sensor/generator systems based on smart material transducers (dielectric elastomers, shape memory alloys, piezoelectrics)

Soft Robotics

Development, modeling, proprioception, and control of soft and continuum robots based on smart material transducers (dielectric elastomers, shape memory alloys)

EDUCATION

Polytechnic University of Bari

Bari, IT

- ◇ Ph.D. in Information and Communication Technology through “Scuola Interpolitecnica di Dottorato”, a high-qualification Ph.D. program involving Polytechnic Universities of Torino, Bari, and Milano, Apr. 2016
- ◇ Master’s Degree in Control Engineering, Dec. 2012 (110/110 with honors)
- ◇ Bachelor’s Degree in Control Engineering, Oct. 2010 (110/110 with honors)

WORK EXPERIENCE

Saarland University,

Saarbrücken, DE

- ◇ Tenure Track Assistant Professor of Adaptive Polymer Systems - Adaptive Polymer Systems Lab **Jan. 2020 - present**
- ◇ Post Doc - Intelligent Material Systems Lab **Apr. 2016 - Dec. 2019**
- ◇ Research Assistant - Intelligent Material Systems Lab **Feb. 2016 - Mar. 2016**

Polytechnic University of Bari,

Bari, IT

- ◇ Research Assistant - Automation and Robotics Lab **Jan. 2016**
- ◇ Ph.D Student - Automation and Robotics Lab **Jan. 2013 - Dec. 2015**

VISITING

Saarland University,

Saarbrücken, DE

Visiting Research Scholar during Ph.D. studies

Feb. 2015 - Dec. 2015

TEACHING EXPERIENCE

Teaching Responsibility in Bachelor/Master Classes

Saarland University

Saarbrücken, DE

- ◇ **Actuators and Sensors with Intelligent Material Systems II**
Period: Spring 2017 - Spring 2024
Level: Bachelor
- ◇ **Actuators and Sensors with Intelligent Material Systems III**
Period: Fall 2018 - Fall 2024
Level: Master
- ◇ **Actuators and Sensors with Intelligent Material Systems IV**
Period: Fall 2017 - Fall 2024
Level: Master

- ◇ **Mechatronic Actuator Systems**
Period: Spring 2024
Level: Master
- ◇ **Smart Materials and Polymers (in cooperation with Prof. Volker Presser and Prof. Markus Gallei)**
Period: Spring 2020 - Spring 2024
Level: Master
- ◇ **Seminar on Modal Analysis (in cooperation with Prof. Kathrin Flaßkamp)**
Period: Spring 2024
Level: Master
- ◇ **Seminar on Soft Robotics**
Period: Fall 2024
Level: Master

Teaching Responsibility in PhD Classes

Polytechnic University of Bari

Bari, IT

- ◇ **Software-Based Methods for Modern Control Systems Design**
Period: Fall 2020
Location: Polytechnic University of Bari, Bari, IT
- ◇ **Modeling of Smart Material Systems**
Period: Fall 2020
Location: Polytechnic University of Bari, Bari, IT
- ◇ **An Introduction to Soft Robotics**
Period: Summer 2024
Location: 4th Inria-DFKI European Summer School on AI (IDESSAI 2024), Saarbrücken, DE

RESEARCH PROJECTS

Saarland University

Saarbrücken, DE

- ◇ **DFG Research Grant S3DEG – The next generation of bi-Stable, Smart, and Self-sensing Dielectric Elastomer Generators**
Goal: Development and Control of Bi-Stable Energy Harvesters Based on Dielectric Elastomer Transducers
Role: PI
Duration: 36 months, starting from September 2024
Individual funding granted: c.ca 429 k€.
- ◇ **DFG project SPP 2206 Cooperative Multistage Multistable Microactuator Systems (Second Funding Period) - DECMAS Phase 2: Dielectric Elastomer Membranes for Cooperative Micro-Actuator/Sensor Concepts**
Goal: Design, Miniaturization, Fabrication, and Cooperative Control of cooperative micro-actuators based on Dielectric Elastomers
Role: PI (project: modeling, control, and self-sensing)
Duration: 36 months, starting from June 2023
Individual funding granted: c.ca 334 k€.
- ◇ **DFG project SPP 2100 Soft Material Robotics Systems (Second Funding Period) - Dielectric Elastomers Phase 2: Soft Material Actuator/Sensor Concepts for Three-Dimensional Soft Robotic Systems**
Goal: Design, Modeling, and Control of three-dimensional soft robotic systems based on Dielectric Elastomers
Role: PI (project: modeling, control, and self-sensing)
Duration: 36 months, starting from July 2022
Individual funding granted: c.ca 284 k€.

- ◇ **DFG project SPP 2206 Cooperative Multistage Multistable Microactuator Systems (First Funding Period) - DECMAS: Dielectric Elastomer Membranes for Cooperative Micro-Actuator/Sensor Concepts**
Goal: Design, Fabrication, Modeling, and Self-Sensing of cooperative micro-actuators based on Dielectric Elastomers
Role: PI (project: modeling, control, and self-sensing)
Duration: 36 months, starting from October 2019
Individual funding granted: c.ca 292 k€.
- ◇ **DFG project SPP 2100 Soft Material Robotics Systems (First Funding Period) - Dielectric Elastomers: Soft Material Actuator/Sensor Concepts for Soft Robotic Systems**
Goal: Design, Modeling, and Control of bi-dimensional soft robotic systems based on Dielectric Elastomers
Role: PI (project: modeling, control, and self-sensing)
Duration: 36 months, starting from July 2019
Individual funding granted: c.ca 299 k€.

EDITORIAL
ACTIVITIES

Editorial Board in International Peer-Reviewed Journals

- ◇ IEEE/ASME Transactions on Mechatronics - Technical Editor (2022 - present)

Editorial Board in International Conferences

- ◇ Technical Program Committee and Track Chair (track: Advanced Motion Control) - IEEE 19th International Conference on Advanced Motion Control AMC 2026, Daegu, South Korea
- ◇ International Program Committee and Associate Editor - 11th International Conference on Control, Decision and Information Technologies CoDIT 2025, Valletta, Malta
- ◇ Associate Editor - 8th IEEE-RAS International Conference on Soft Robotics RoboSoft 2025, Lausanne, Switzerland
- ◇ Programme Committee - SPIE Smart Structures + Nondestructive Evaluation 2025 conference SSN02: Electroactive Polymer Actuators, Sensors, and Devices (EAPAD) 2025, Vancouver, Canada
- ◇ Associate Editor - 11th Vienna International Conference on Mathematical Modelling MATHMOD 2025, Vienna, Austria
- ◇ Track co-chair (track: Control Systems) - 33th IEEE International Symposium on Industrial Electronics (ISIE) 2024, Ulsan, South Korea
- ◇ Technical Program Committee - IEEE 18th International Conference on Advanced Motion Control AMC 2024, Kyoto, Japan
- ◇ Programme Committee - SPIE Smart Structures + Nondestructive Evaluation 2024 conference SSN02: Electroactive Polymer Actuators, Sensors, and Devices (EAPAD) 2024, Long Beach, California, United States
- ◇ Track co-chair (track: Control Systems) - 32th IEEE International Symposium on Industrial Electronics (ISIE) 2023, Helsinki/Espoo, Finland
- ◇ Associate Editor - 10th Vienna International Conference on Mathematical Modelling MATHMOD 2022, Vienna, Austria
- ◇ Conference Committee Member - 1st International Electronic Conference on Actuator Technology: Materials, Devices and Applications IeCAT 2020, online conference

Organization of Special Sessions at International Conferences

- ◇ Co-organizer of Workshop “Soft Robotic Actuation and Sensing Based on Functional Materials” - 8th IEEE-RAS International Conference on Soft Robotics RoboSoft 2025, Lausanne, Switzerland

- ◇ Co-organizer of Minisymposium “Modeling and Control of Smart Material Systems and Structures” - 10th Vienna International Conference on Mathematical Modelling MATHMOD 2022, Vienna, Austria
- ◇ Co-organizer of Special Session “Intelligent Systems and Technologies for Advanced Manufacturing” - 7th International Conference on Control, Decision and Information Technologies CoDIT 2020, Prague, Czech Republic
- ◇ Organizer of Minisymposium “Modeling and Control of Smart Material Systems” - 9th Vienna International Conference on Mathematical Modelling MATHMOD 2018, Vienna, Austria

HONORS AND
AWARDS

Article selected for the Highlights of 2024 **February 2025**
IOP Smart Materials and Structures - “Energy-based modeling of rate-independent hysteresis and viscoelastic effects in dielectric elastomer actuators” (reference [62.j] in the publications list)

IOP Trusted Reviewer **May 2024**
Certificate received in recognition of an exceptionally high level of peer review competency.

ASME 2022 Student Hardware Award - Third Place **Sep. 2022**
ASME Smart Materials, Adaptive Structures, and Intelligent Structures Conference - “A Novel Compact Concept Design of an SMA Based Endoscope” (reference [107.c] in the publications list)

IEEE Best Paper Award **Apr. 2021**
4th IEEE International Conference on Soft Robotics - “Bistable Actuation in Multi-DoF Soft Robotic Modules Driven by Rolled Dielectric Elastomer Actuators” (reference [83.c] in the publications list)

ASME 2018 Ephraim Garcia Best Paper Award **Sep. 2019**
ASME 2019 Smart Materials, Adaptive Structures, and Intelligent Systems Conference - “A novel dielectric elastomer membrane actuator concept for high-force applications” (reference [21.j] in the publications list)

SPIE Honorable Mention Award **Mar. 2018**
SPIE Smart Structures and Materials+ Nondestructive Evaluation and Health Monitoring - “Self-sensing for robust automatic charge management of dielectric elastomer generators” (reference [34.c] in the publications list)

IEEE/ASME Best Student Paper Award **Aug. 2016**
IEEE/ASME International Conference on Mechatronic and Embedded Systems and Applications - “Self-Sensing at Low Sampling-To-Signal Frequency Ratio: an Improved Algorithm for Dielectric Elastomer Actuators” (reference [21.c] in the publications list)

Admission to High-Qualification Ph.D Program “Scuola Interpolitecnica di Dottorato” **May 2014**
A high-qualification Ph.D program coordinated by the Polytechnic University of Torino, admission restricted to 24 engineering Ph.D students per year among the three Italian Polytechnic Universities of Torino, Bari, and Milano

PLENARY TALKS

Modeling, Control, and Self-Sensing of Dielectric Elastomers: from Actuators to Soft Robots **Mar. 2025**
SAMCON 2025 - 11th IEEEJ international workshop on Sensing, Actuation, Motion Control, and Optimization, Shimane, Japan

Invited by Prof. Tomoyuki Shimono

INVITED TALKS

Leveraging bi-stability and model-based approaches in dielectric elastomer soft robots **Mar. 2025**

SPIE Smart Structures + Nondestructive Evaluation 2025 - Electroactive Polymer Actuators, Sensors, and Devices, Vancouver, Canada

Invited by Prof. Stefan Seelecke

Silicone-based dielectric elastomer actuators for intelligent soft robotic systems **Apr. 2024**

RoboSoft 2024 - IEEE International Conference on Soft Robotics, Workshop “Challenges and Opportunities of Electrically-Driven Soft Actuators”, San Diego, US

Invited by Prof. Siyi Xu, Dr. Michelle Ching-Sum Yuen, and Prof. Robert Wood (Workshop organizers)

A bi-stable soft robotic module actuated by dielectric elastomer artificial muscles: design, characterization, modeling, and control **Apr. 2023**

RoboSoft 2023 - IEEE International Conference on Soft Robotics, Workshop “Bi- & Multi-Stability in Soft Robots”, Singapore

Invited by Prof. Amir Gat, Prof. Robert Shepard, Ezra Ben Abu, Dr. Yoav Matia (Workshop organizers)

From Smart Materials to Smart Systems –

Modeling, Control, and Self-Sensing of Dielectric Elastomers **Jun. 2021**

EuroEAP 2021 - International conference on Electromechanically Active Polymer (EAP) transducers & artificial muscles, online conference

Invited by Prof. Edwin Jager

Modeling of Dielectric Elastomer Membrane Actuators:

From Material to Applications

Oct. 2018

2018 Sino-German Symposium - Complex material structures for functional ferro-, pyro- and piezoelectric ceramics, polymers and composites, Shanghai, CN

Invited by Prof. Reimund Gerhard and Prof. Xiaoqing Zhang

Advanced Applications of Motion Control Technology -

Modeling, Control and Application of Smart Materials Based Actuators and Systems **Oct. 2016**

The 42nd Annual Conference of the IEEE Industrial Electronics Society (IECON2016), co-organized and co-presented with Dr. Leonardo Riccardi, Florence, IT

Invited by Prof. Kenji Natori

SERVICES

Committees

- ◇ IEEE IES Technical Committee on Motion Control, Sub-Committee Chair on High-precision Control, 2024 - Present
- ◇ EuroEAP Society, Conference Committee Member, 2024 - Present
- ◇ VDE GMM ACTUATOR conference Program Committee, 2024 - Present

Memberships in Scientific Committees

- ◇ Institute of Electrical and Electronics Engineers (IEEE), Member 2016 - 2023, Senior Member 2023 - Present (societies: CSS, RAS, IES)
- ◇ EuroEAP Society, European Society for Electromechanically Active Polymer Transducers & Artificial Muscles, 2021 - present
- ◇ International Federation of Automatic Control (IFAC), Affiliate 2024 - present

Publication Summary

- ◇ Peer Reviewed Journal Papers: 69
- ◇ International Conference Proceedings: 147
- ◇ Editorial Contributions in Books: 3
- ◇ Patents: 1

Citation indexes

- ◇ Google Scholar: h-index 26, n. of citations: 2849
Link: <https://scholar.google.it/citations?user=F7K3374AAAAJ&hl=it>
- ◇ Scopus: h-index 23, n. of citations: 2033
Link: <https://www.scopus.com/authid/detail.uri?authorId=55970038200>

Journal Papers

- [69.j] M. Kohl, C. Ament, G. Arivanandhan, T. Bechtold, P. Conrad, S. Croce, V. Gottwald, M. Hoffmann, J. Hubertus, A. Kopp, Z. Li, M. Olbrich, K. Poletkin, A. Priuli, **G. Rizzello**, A. Schuetz, G. Schultes, S. Seelecke, L. Seigner, H. Shahsavari, M. B. Shamim, M. Sielenkämper, G. K. Tshikwand, U. Wallrabe, P. Weber, F. Wendler, and S. Wulfinghoff, “Active Bi- and Multistability in Cooperative Microactuator Systems,” *Sensors and Actuators Reports*, pp. 1-55, May. 2025 (DOI: 10.1016/j.snr.2025.100338).
- [68.j] G. Soleti, P. R. Massenio, J. Kunze, and **G. Rizzello**, “Model-Based Robust Position Control of an Underactuated Dielectric Elastomer Soft Robot,” *IEEE Transactions on Robotics*, vol. 41, pp. 1693-1710, Feb. 2025 (DOI: 10.1109/TRO.2025.3539184).
- [67.j] S. Addario, S. Gratz-Kelly, D. Naso, **G. Rizzello**, and G. Moretti, “An experimental parametric analysis of the acoustic response in dielectric elastomer loudspeakers,” *Journal of Vibration and Control*, pp. 1-8, Aug. 2024 (DOI: 10.1177/10775463241273022).
- [66.j] T. P. Willian, S. Pohl, D. Bruch, **G. Rizzello**, P. Motzki, G. Kickelbick, and S. Seelecke, “Effects of Solvents on the Material Properties of Screen-printed Electrodes and a PDMS Dielectric for Dielectric Elastomer Transducers,” *Advanced Engineering Materials*, vol. 26, no. 10, p. 2301736, May 2024 (DOI: 10.1002/adem.202301736).
- [65.j] S. Gratz-Kelly, T. F. Krüger, S. Seelecke, **G. Rizzello**, and G. Moretti, “A tri-modal dielectric elastomer actuator integrating linear actuation, sound generation, and self-sensing capabilities,” *Sensors and Actuators A: Physical*, vol. 372, p. 115332, Jul. 2024 (DOI: 10.1016/j.sna.2024.115332).
- [64.j] S. Seelecke, **G. Rizzello**, and P. Motzki, “Elektroaktive Polymere und Formgedächtnislegierungen: Smarte und Energieeffiziente Antriebssysteme für die Produktion,” *atp magazin*, vol. 66, no. 3, pp. 52-59, Mar. 2024 (DOI: 10.17560/atp.v66i3.2708).
- [63.j] J. Prechtel, M. Baltés, K. Flaßkamp, and **G. Rizzello**, “Sensorless proprioception in multi-DoF dielectric elastomer soft robots via system-level self-sensing,” *IEEE/ASME Transactions on Mechatronics*, vol. 29, no. 6, pp. 4365-4376, Dec. 2024 (DOI: 10.1109/TMECH.2024.3375923).
- [62.j] **G. Rizzello**, “Energy-based modeling of rate-independent hysteresis and viscoelastic effects in dielectric elastomer actuators,” *Smart Materials and Structures*, vol. 33, no. 5, p. 055027, May 2024 (DOI: 10.1088/1361-665X/ad389f).

- [61.j] Y. Olsommer, F. R. Ihmig, and **G. Rizzello**, “Physics-based modeling of ferroelectric hysteresis for ceramic capacitors in inductively coupled microstimulators,” *IEEE Transactions on Power Electronics*, vol. 39, no. 6, pp. 7696-7707, Jun. 2024 (DOI: 10.1109/TPEL.2024.3361075).
- [60.j] Y. Goergen, **G. Rizzello**, and P. Motzki, “Systematic Methodology for an Optimized Design of Shape Memory Alloy-Driven Continuum Robots,” *Advanced Engineering Materials*, vol. 26, no. 2, p. 2301502, Jan. 2024 (DOI: 10.1002/adem.202301502).
- [59.j] C. Perri, B. Holz, P. R. Massenio, D. Naso, and **G. Rizzello**, “Design, Modeling, and Experimental Validation of a High Voltage Driving Circuit for Dielectric Elastomer Actuators,” *IEEE Transactions on Industrial Electronics*, vol. 71, no. 5, pp. 5083-5093, May 2024 (DOI: 10.1109/TIE.2023.3288190).
- [58.j] M. Bolignari, **G. Rizzello**, L. Zaccarian, and M. Fontana, “Lightweight Human-Friendly Robotic Arm based on Transparent Hydrostatic Transmissions,” *IEEE Transactions on Robotics*, vol. 39, no. 5, pp. 4051-4064, Oct. 2023 (DOI: 10.1109/TRO.2023.3290310).
- [57.j] **G. Rizzello**, “Robust output regulation of a class of smart actuators described by a minimum phase LPV dynamics,” *Mechatronics*, vol. 94, p. 103003, Oct. 2023 (DOI: 10.1016/j.mechatronics.2023.103003).
- [56.j] M. K. Hoffmann, L. Heib, G. Moretti, **G. Rizzello**, and K. Flaßkamp, “Optimal operation of dielectric elastomer wave energy converters under harmonic and stochastic excitation,” *GAMM Mitteilungen*, p. e202300010, May 2023 (DOI: 10.1002/gamm.202300010).
- [55.j] P. R. Massenio, M. Tipaldi, **G. Rizzello**, E. Brescia, G. L. Cascella, and D. Naso, “Gain-Scheduled Structured Control in DC Microgrids,” *IEEE Transactions on Control Systems Technology*, vol. 31, no. 6, pp. 2571-2583, Nov. 2023 (DOI: 10.1109/TCST.2023.3269227).
- [54.j] S. Seelecke, J. Neu, S. Croce, J. Hubertus, G. Schultes, and **G. Rizzello**, “Dielectric Elastomer Cooperative Microactuator Systems—DECMAS,” *Actuators*, vol. 12, no. 4, p. 141, March 2023 (DOI: 10.3390/act12040141).
- [53.j] M. A. Mandolino, D. Scholtes, F. Ferrante, and **G. Rizzello**, “A Physics-Based Hybrid Dynamical Model of Hysteresis in Polycrystalline Shape Memory Alloy Wire Transducers,” *IEEE/ASME Transactions on Mechatronics*, vol. 28, no. 5, pp. 2529-2540, Oct. 2023 (DOI: 10.1109/TMECH.2023.3253250).
- [52.j] J. Hubertus, S. Croce, J. Neu, S. Seelecke, **G. Rizzello**, and G. Schultes, “Laser Structuring of Thin Metal Films of Compliant Electrodes on Dielectric Elastomers,” *Advanced Functional Materials*, vol. 33, no. 16, p. 2214176, Apr. 2023 (DOI: 10.1002/adfm.202214176).
- [51.j] S. Gratz-Kelly, T. Krüger, **G. Rizzello**, S. Seelecke, and G. Moretti, “An audio-tactile interface based on dielectric elastomer actuators,” *Smart Materials and Structures*, vol. 32, no. 3, p. 034005, Mar. 2023 (DOI: 10.1088/1361-665X/acb6da).
- [50.j] **G. Rizzello**, “A Review of Cooperative Actuator and Sensor Systems Based on Dielectric Elastomer Transducers,” *Actuators*, vol. 12, no. 2, p. 46, Jan. 2023 (DOI: 10.3390/act12020046).
- [49.j] T. P. Willian, B. Fasolt, P. Motzki, **G. Rizzello**, and S. Seelecke, “Effects of Electrode Materials and Compositions on the Resistance Behavior of Dielectric Elastomer Transducers,” *Polymers*, vol. 15, no. 2, p. 310, Jan. 2023 (DOI: 10.3390/polym15020310).

- [48.j] J. Neu, S. Croce, T. Willian, J. Hubertus, G. Schultes, S. Seelecke, and **G. Rizzello**, “Distributed Electro-Mechanical Coupling Effects in a Dielectric Elastomer Membrane Array,” *Experimental Mechanics*, vol. 63, pp. 79-95, Jan. 2023 (DOI: 10.1007/s11340-022-00892-0).
- [47.j] M. Baltes, J. Kunze, J. Prechtel, S. Seelecke, and **G. Rizzello**, “A bi-stable soft robotic bendable module driven by silicone dielectric elastomer actuators: design, characterization, and parameter study,” *Smart Materials and Structures*, vol. 31, no. 11, p. 114002, Nov. 2022 (DOI: 10.1088/1361-665X/ac96df).
- [46.j] S. Croce, J. Neu, G. Moretti, J. Hubertus, G. Schultes, and **G. Rizzello**, “Finite element modeling and validation of a soft array of spatially coupled dielectric elastomer transducers,” *Smart Materials and Structures*, vol. 31, no. 8, p. 084001, Aug. 2022 (DOI: 10.1088/1361-665X/ac78ad).
- [45.j] S. Gratz-Kelly, **G. Rizzello**, M. Fontana, S. Seelecke, and G. Moretti, “A Multi-Mode, Multi-Frequency Dielectric Elastomer Actuator,” *Advanced Functional Materials*, vol. 33, no. 34, p. 2201889, Aug. 2022 (DOI: 10.1002/adfm.202201889).
- [44.j] R. Britz, **G. Rizzello**, and P. Motzki, “High-Speed Antagonistic Shape Memory Actuator for High Ambient Temperatures,” *Advanced Engineering Materials*, vol. 24, no. 9, p. 2200205, Sep. 2022 (DOI: 10.1002/adem.202200205).
- [43.j] G. Moretti, **G. Rizzello**, M. Fontana, and S. Seelecke, “High-frequency voltage-driven vibrations in dielectric elastomer membranes,” *Mechanical Systems and Signal Processing*, vol. 168, p. 108677, Apr. 2022 (DOI: 10.1016/j.ymssp.2021.108677).
- [42.j] J. Prechtel, J. Kunze, G. Moretti, D. Bruch, S. Seelecke, and **G. Rizzello**, “Modeling and experimental validation of thin, tightly rolled dielectric elastomer actuators,” *Smart Materials and Structures*, vol. 31, no. 1, p. 015008, Nov. 2021 (DOI: 10.1088/1361-665X/ac34be).
- [41.j] S. Croce, J. Neu, J. Hubertus, S. Seelecke, G. Schultes, and **G. Rizzello**, “Model-Based Design Optimization of Soft Polymeric Domes Used as Non-linear Biasing Systems for Dielectric Elastomer Actuators,” *Actuators*, vol. 10, no. 9, p. 209, Aug. 2021 (DOI: 10.3390/act10090209).
- [40.j] J. Hubertus, J. Neu, S. Croce, **G. Rizzello**, S. Seelecke, and G. Schultes, “Nanoscale Nickel-based Thin Films as Highly Conductive Electrodes for Dielectric Elastomer Applications with Extremely High Stretchability up to 200 %,” *ACS Applied Materials & Interfaces*, vol. 13, no. 33, pp. 39894-39904, Aug. 2021 (DOI: 10.1021/acsami.1c10686).
- [39.j] J. Neu, J. Hubertus, S. Croce, G. Schultes, S. Seelecke, and **G. Rizzello**, “Fully Polymeric Domes as High-Stroke Biasing System for Soft Dielectric Elastomer Actuators,” *Frontiers in Robotics and AI*, vol. 8, p. 171, Jun. 2021 (DOI: 10.3389/frobt.2021.695918).
- [38.j] J. Kunze, J. Prechtel, D. Bruch, B. Fasolt, S. Nalbach, P. Motzki, S. Seelecke, and **G. Rizzello**, “Design, Manufacturing, and Characterization of Thin, Core-Free, Rolled Dielectric Elastomer Actuators,” *Actuators*, vol. 10, no. 4, p. 69, Mar. 2021 (DOI: 10.3390/act10040069).
- [37.j] M. A. Mandolino, F. Ferrante, and **G. Rizzello**, “A Hybrid Dynamical Modeling Framework for Shape Memory Alloy Wire Actuated Structures,” *IEEE Robotics and Automation Letters*, vol. 6, no. 2, pp. 3886-3893, Apr. 2021 (DOI: 10.1109/LRA.2021.3067254).
- [36.j] M. Bolognari, **G. Rizzello**, L. Zaccarian, and M. Fontana, “Smith-predictor-based torque control of a rolling diaphragm hydrostatic transmission,” *IEEE Robotics and Automation Letters*, vol. 6, no. 2, pp. 2970-2977, Apr. 2021 (DOI: 10.1109/LRA.2021.3062310).

- [35.j] F. Simone, **G. Rizzello**, S. Seelecke, and P. Motzki, “A soft five-fingered hand actuated by Shape Memory Alloy wires: design, manufacturing, and evaluation,” *Frontiers in Robotics and AI*, vol. 7, p. 608841, Dec. 2020 (DOI: 10.3389/frobt.2020.608841).
- [34.j] P. R. Massenio, **G. Rizzello**, G. Comitangelo, D. Naso, and S. Seelecke, “Reinforcement Learning Based Minimum Energy Position Control of Dielectric Elastomer Actuators,” *IEEE Transactions on Control Systems Technology*, vol. 29, no. 4, pp. 1674-1688, Jul. 2021 (DOI: 10.1109/TCST.2020.3022951).
- [33.j] **G. Rizzello**, P. Loew, L. Agostini, M. Fontana, and S. Seelecke, “A lumped parameter model for strip-shaped dielectric elastomer membrane transducers with arbitrary aspect ratio,” *Smart Materials and Structures*, vol. 29, no. 11, p. 115030, Sep. 2020 (DOI: 10.1088/1361-665X/abb09e).
- [32.j] P. Montegiglio, C. Maruccio, G. Acciani, **G. Rizzello**, and S. Seelecke, “Nonlinear multi-scale dynamics modeling of piezoceramic energy harvesters with ferroelectric and ferroelastic hysteresis,” *Nonlinear Dynamics*, vol. 100, pp. 1985-2003, May 2020 (DOI: 10.1007/s11071-020-05660-0).
- [31.j] P. Linnebach, **G. Rizzello**, and S. Seelecke, “Design and Validation of a Dielectric Elastomer Membrane Actuator Driven Pneumatic Pump,” *Smart Materials and Structures*, vol. 29, no. 7, p. 075021, Jul. 2020 (DOI: 10.1088/1361-665X/ab8a01).
- [30.j] S. Nalbach, R. M. Banda, S. Croce, **G. Rizzello**, D. Naso, and S. Seelecke, “TModeling and Design Optimization of a Rotational Soft Robotic System Driven by Double Cone Dielectric Elastomer Actuators,” *Frontiers in Robotics and AI*, vol. 6, p. 150, Jan. 2020 (DOI: 10.3389/frobt.2019.00150).
- [29.j] **G. Rizzello**, P. Serafino, D. Naso, and S. Seelecke, “Towards Sensorless Soft Robotics: Self-Sensing Stiffness Control of Dielectric Elastomer Actuators,” *IEEE Transactions on Robotics*, vol. 39, no. 1, pp. 174-188, Feb. 2020 (DOI: 10.1109/TRO.2019.2944592).
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May 13, 2025