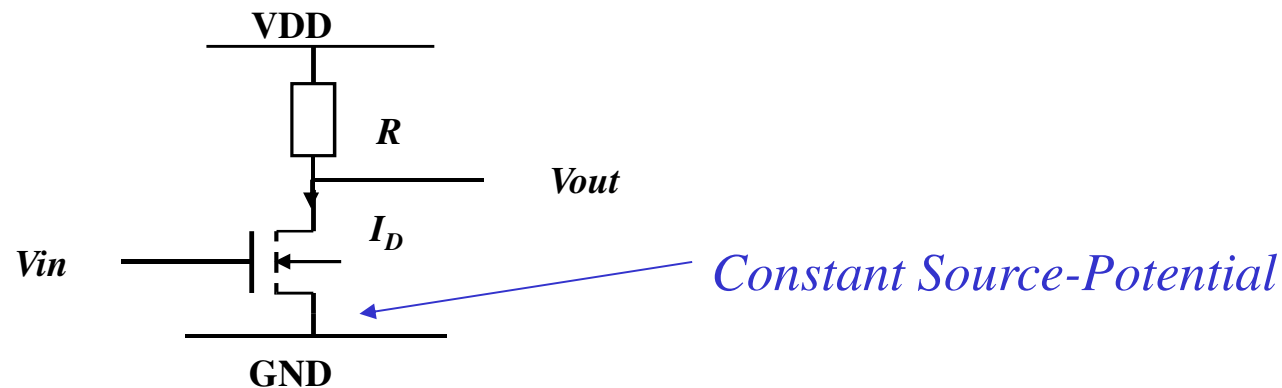


# Chapter 4

## Basics of analog MOS IC

- Inverter Circuit
- Differential Amplifier
- Current Mirror

## A common source circuit



Input  $V_{in}$  low

⇒ NMOS off

⇒ Output  $V_{out} = V_{DD} = \text{High}$

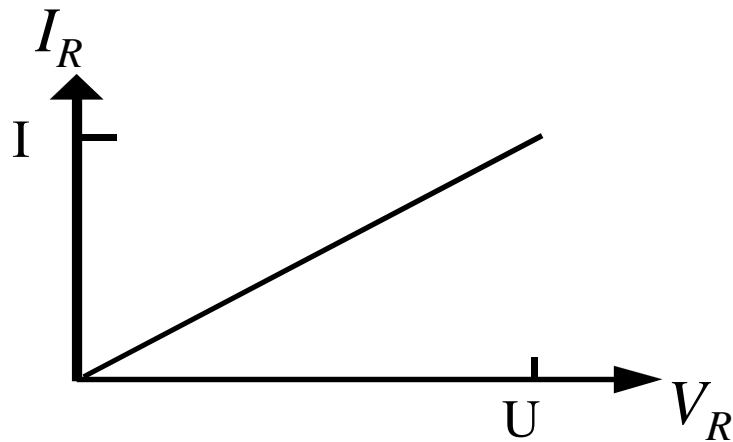
Input  $V_{in}$  high

⇒ drain current is flowing

⇒ Output  $V_{out} = V_{DD} - I_D * R = \text{Low}$

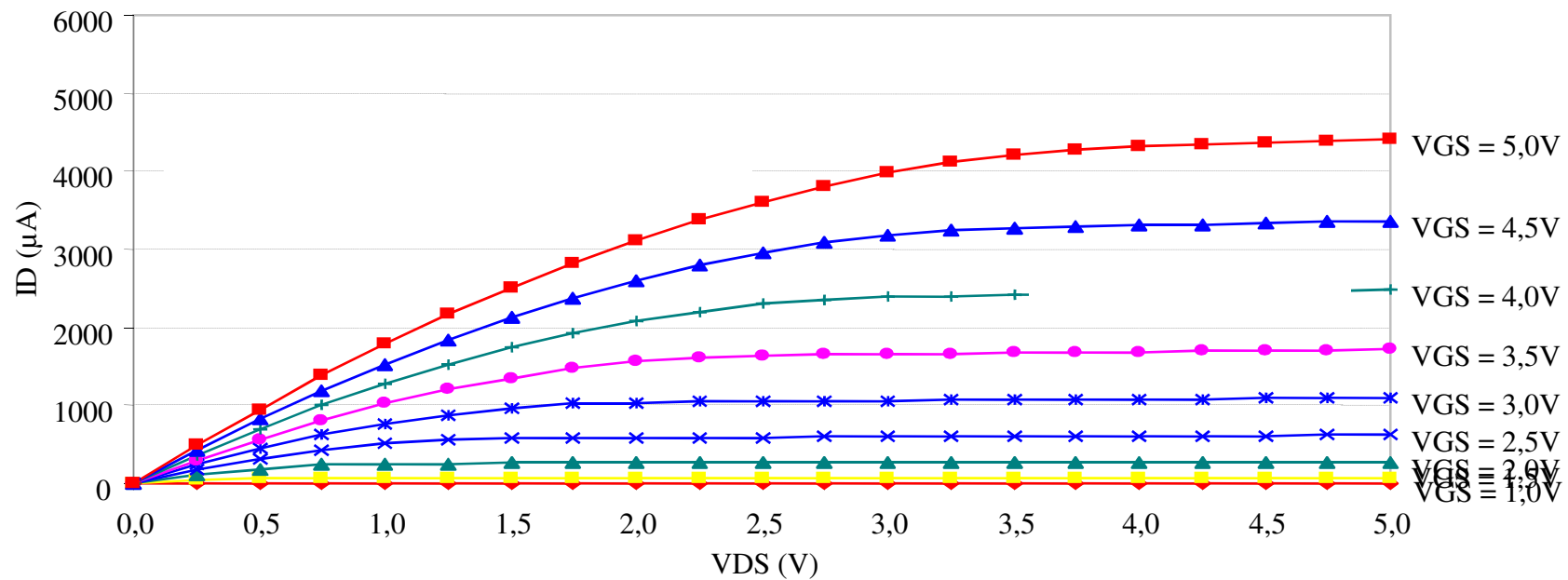
It is an inverter circuit.

# Characteristic curves of resistor and MOSFET

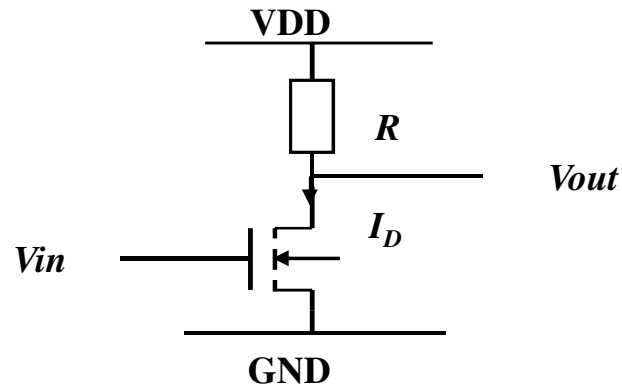


$$I_R = I_D$$

$$V_R = V_{DD} - V_{DS}$$

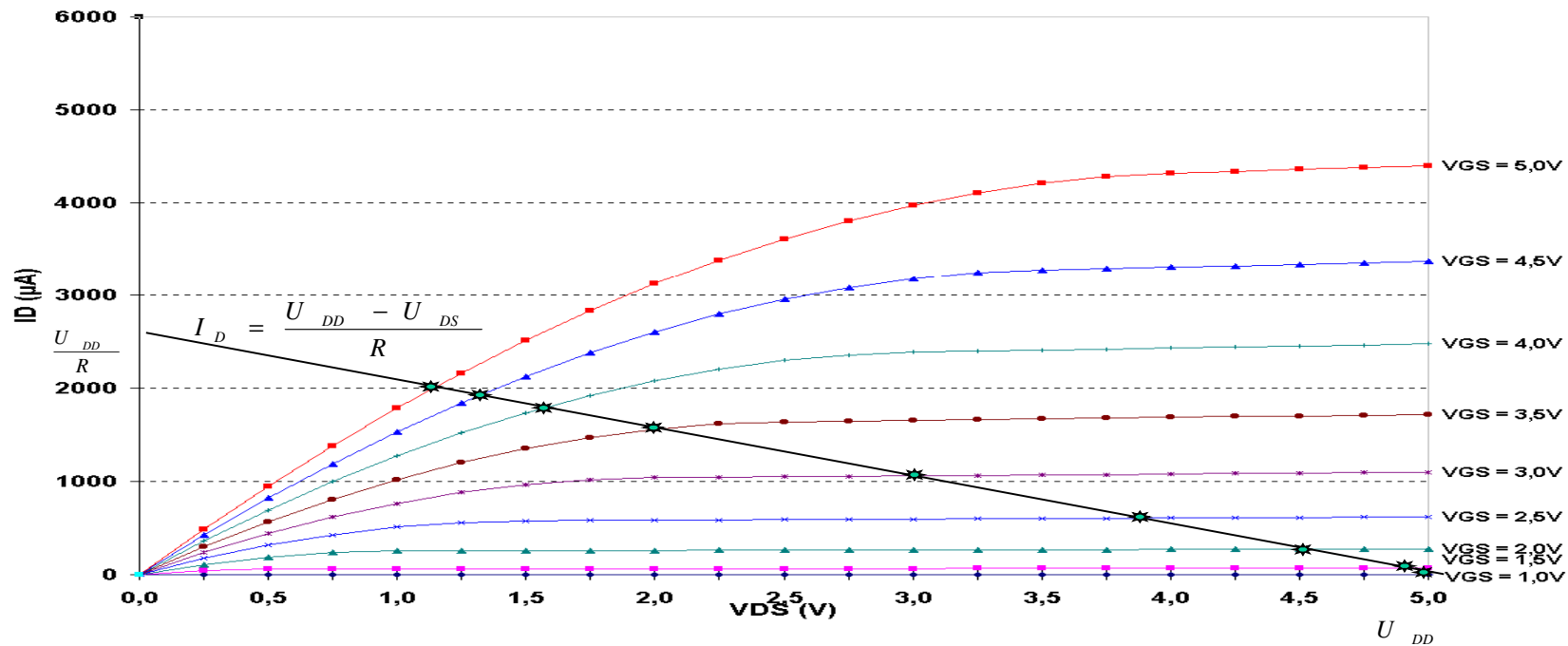


# Determination of the inverter characteristic

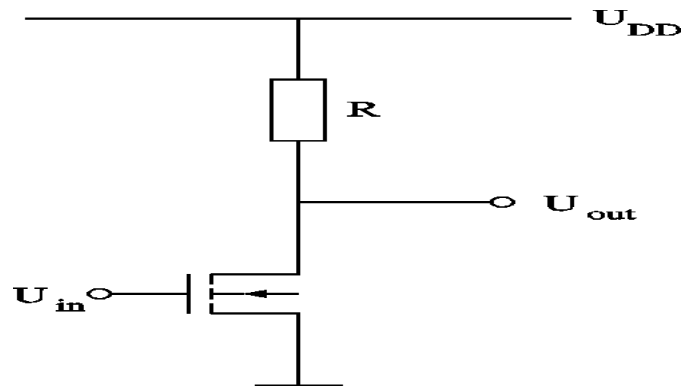


$$I_R = I_D = \frac{V_{DD} - V_{DS}}{R}$$

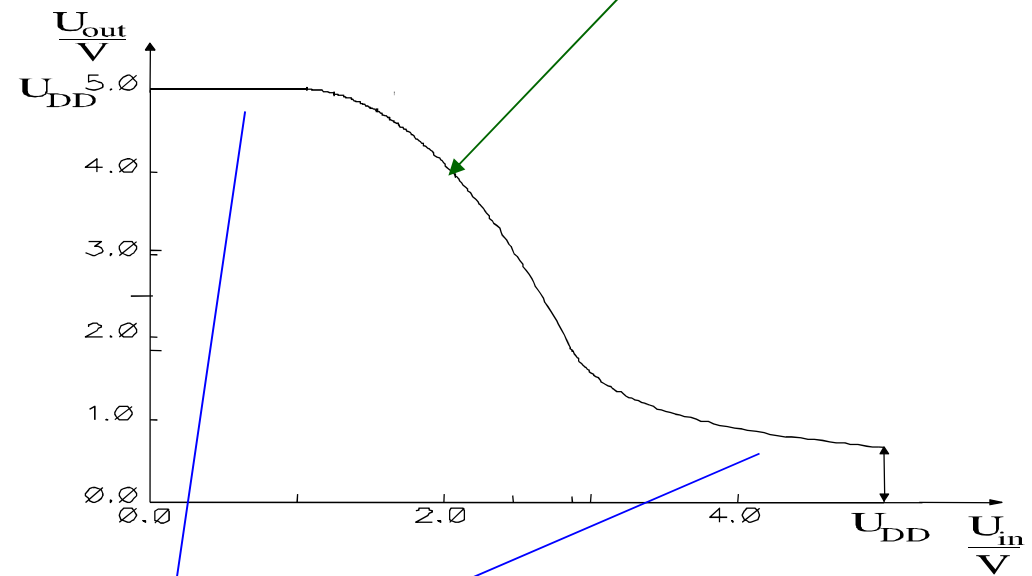
Ausgangskennlinie



# Inverter transfer characteristic and operation regions



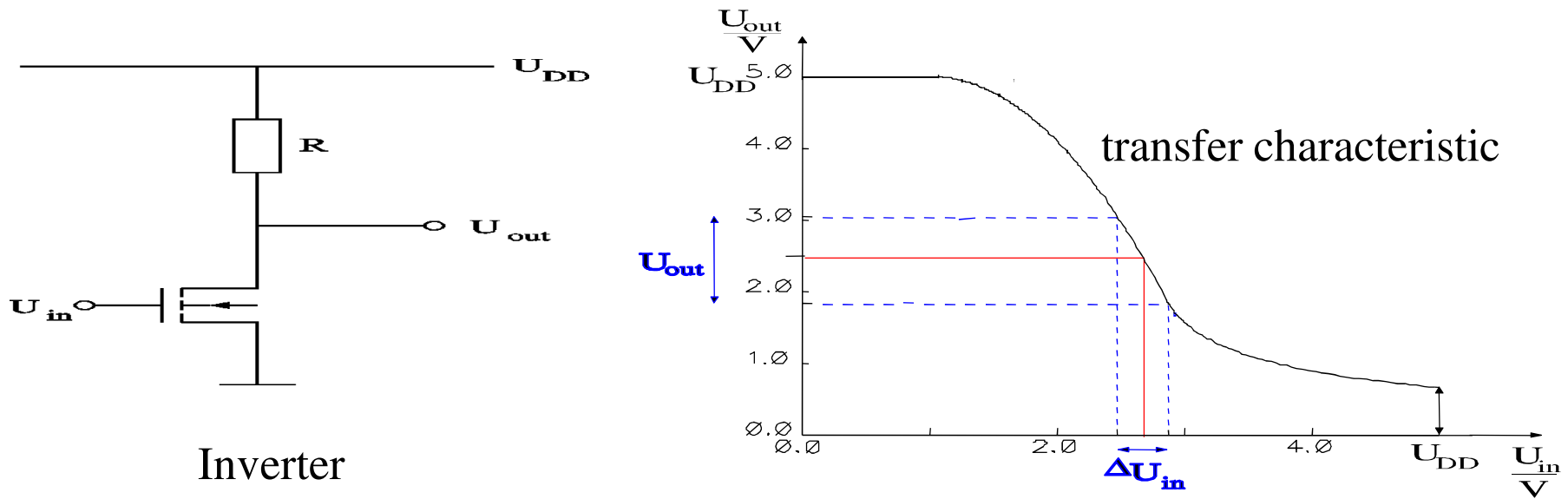
Inverter



Inverter characteristic

Digital technology

# Inverter Transfer Characteristic



Large signal < > Small signal

## Calculation of Operation Point

Given;

$$V_{DD} = 5V$$

$$V_T = 1V$$

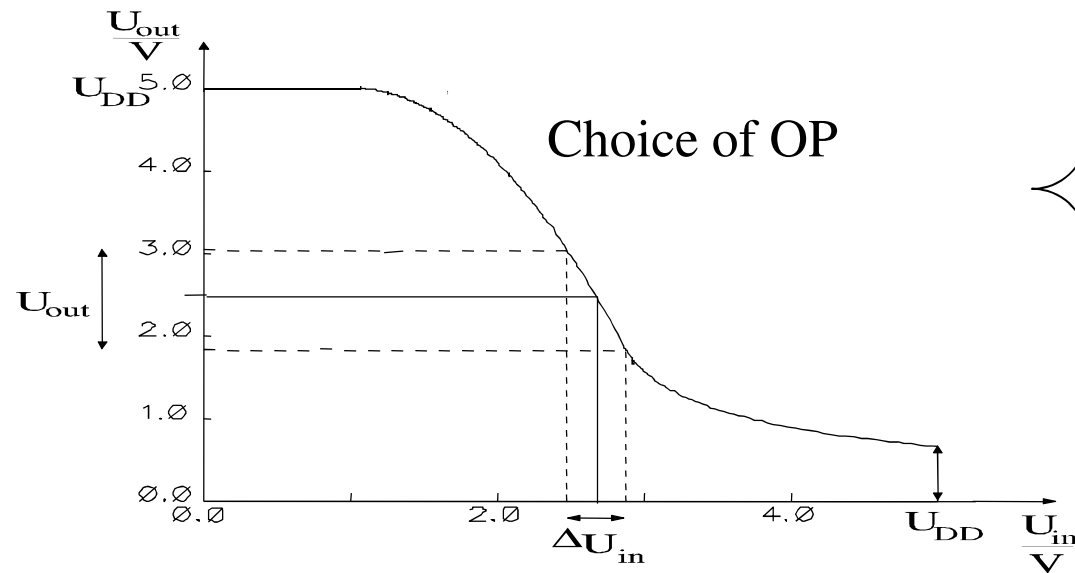
From circuit

$$U_{in} = U_{GS}$$

$$U_{out} = U_{DS} = U_{DD} - I_D \cdot R$$

$$I_D = \frac{\beta}{2} \cdot (U_{GS} - U_T)^2$$

Operation point  $V_{in}$ ,  $V_{out}$ , ( $I_D$ ,  $R$ ,  $W/L$ )



$$\left\{ \begin{array}{l} U_{in} = \frac{U_{DD}}{2} = 2.5 V \\ U_{out} = \frac{U_{DD}}{2} = 2.5 V \\ I_R = 250 \mu A \end{array} \right.$$

## Dimensioning of R , W/L

$$U_{DD} - U_{out} = I_R \cdot R$$

$$\Rightarrow R = 10 k \Omega$$

$$U_{G_{eff}} = U_{in} - U_T = 1.5 V < U_{DS} = 2.5 V$$

$\Rightarrow$  Transistor is in the saturation region

$$I_D = \frac{\beta}{2} (U_{GS} - U_T)^2 = 250 \mu A$$

$$I_D = \frac{\beta}{2} (U_{GS} - U_T)^2 = 250 \mu A$$

$$t_{ox} = 50 \text{ nm}$$

$$\beta_0 = \mu_n \cdot \frac{\epsilon_{ox}}{t_{ox}} = 93,2 \mu A / V^2$$

$$\beta = \frac{W}{L} \cdot \beta_0$$

$$\frac{W}{L} = \frac{2 \cdot I_D}{\beta_0 \cdot (U_{GS} - U_T)^2}$$

$$= \frac{2 \cdot 250 \mu A}{93,2 \frac{\mu A}{V^2} \cdot (1,5 V)^2}$$

$$= 2,38$$



$$W/L = 2.38$$

Dimensioning for a 1μm-process

$$L=1\mu\text{m} \quad W=2.38\mu\text{m?}$$

No, **mask resolution were too fine**

$$L=10\mu\text{m} \quad W=23.8\mu\text{m?}$$

No, area too large

A reasonable solution:

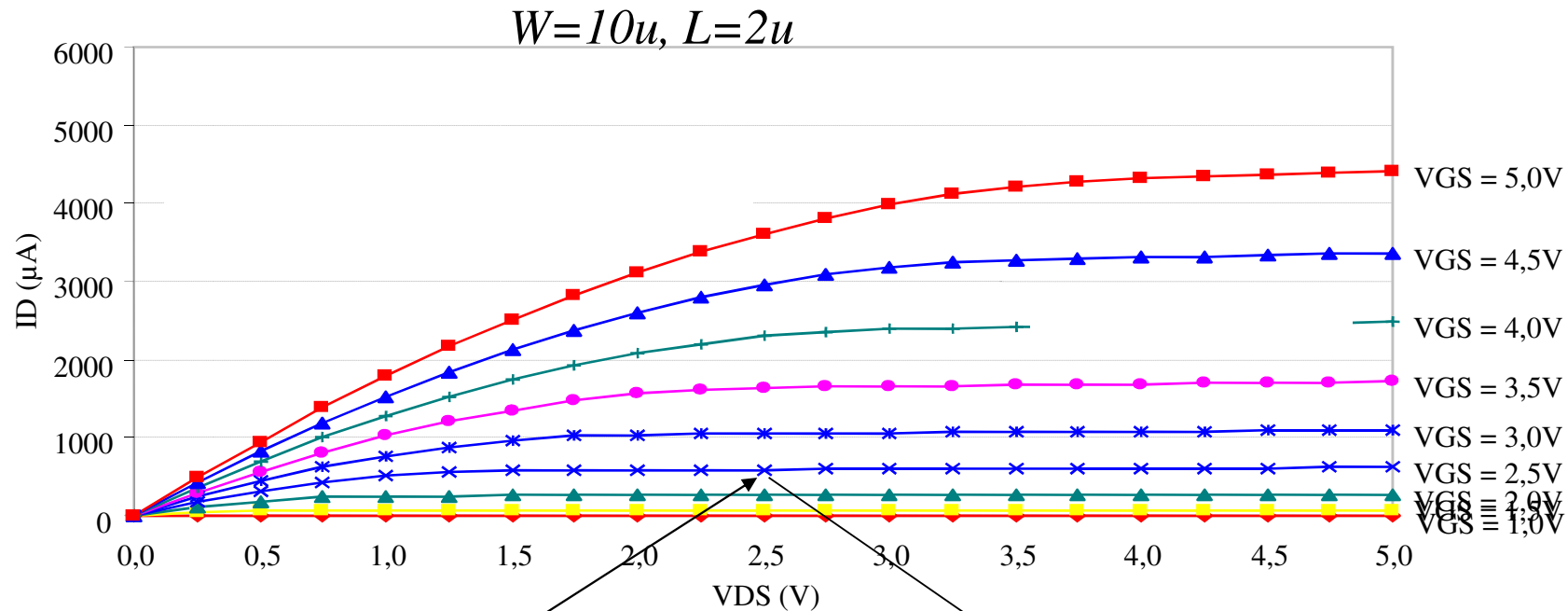
$$L=1\mu\text{m} \quad W=2.4\mu\text{m}$$

$$W/L = 2.38$$

Realization with processes

W(μm)	L(μm)	W/L
3,5	1,5	2,33
2,4	1	2,4
1,7	0,7	2,43
1,2	0,5	2,4
0,85	0,35	2,43

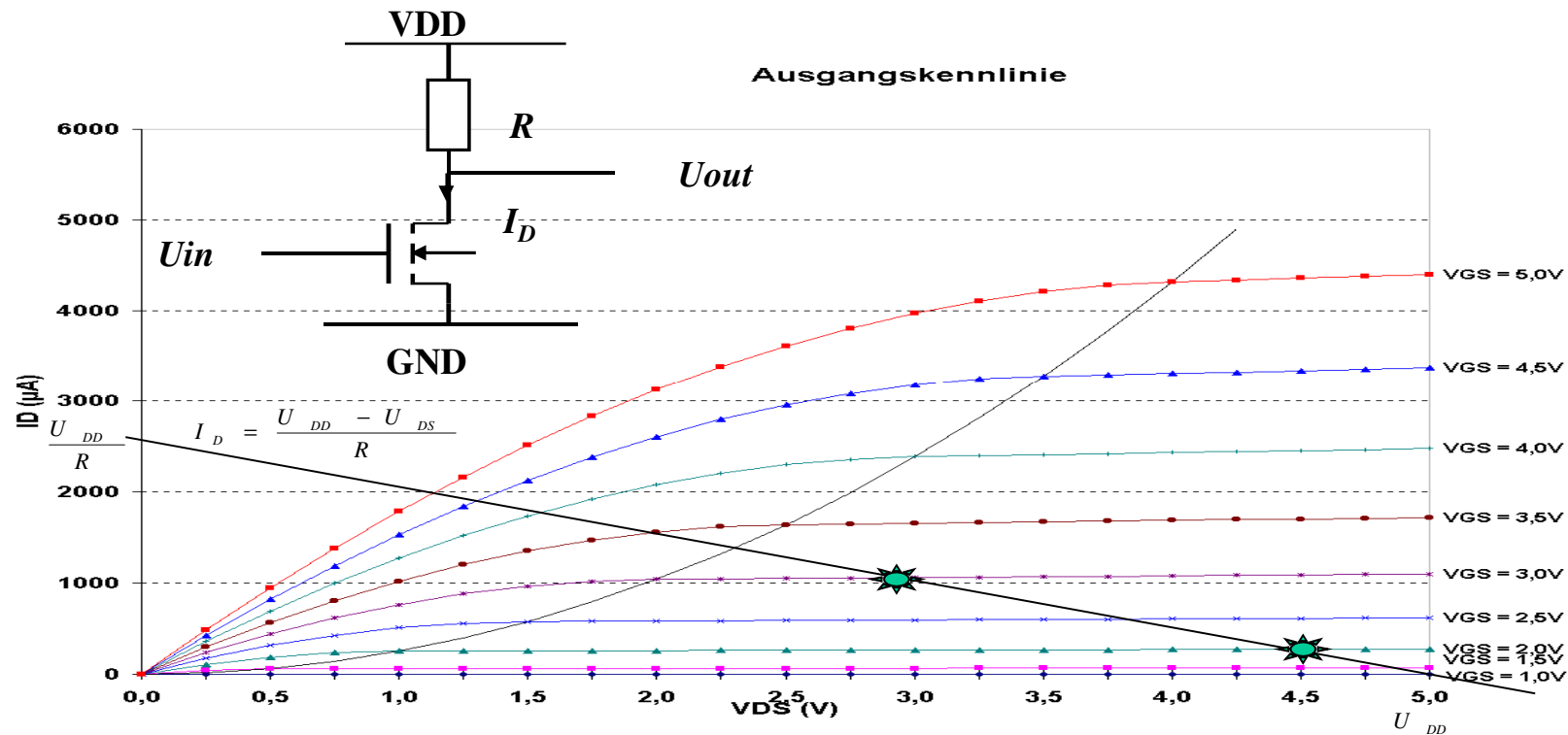
## Calculation of operation point using output characteristics



Objective:  $I_D = 250 \mu A$

$$W/L = 250 \mu A / 600 \mu A * 10\mu m / 2\mu m = 2,1$$

# Calculation of the gain of an inverter



$$\Delta I_D = G \cdot \Delta U_{in}$$

$$\Delta U_{out} = -R \cdot \Delta I_D$$

$$\Rightarrow \Delta U_{out} = -R \cdot G \cdot \Delta U_{in}$$

$$\Delta U_{in} = \Delta U_{GS}$$

$$\Delta U_{out} = \Delta U_{DS}$$

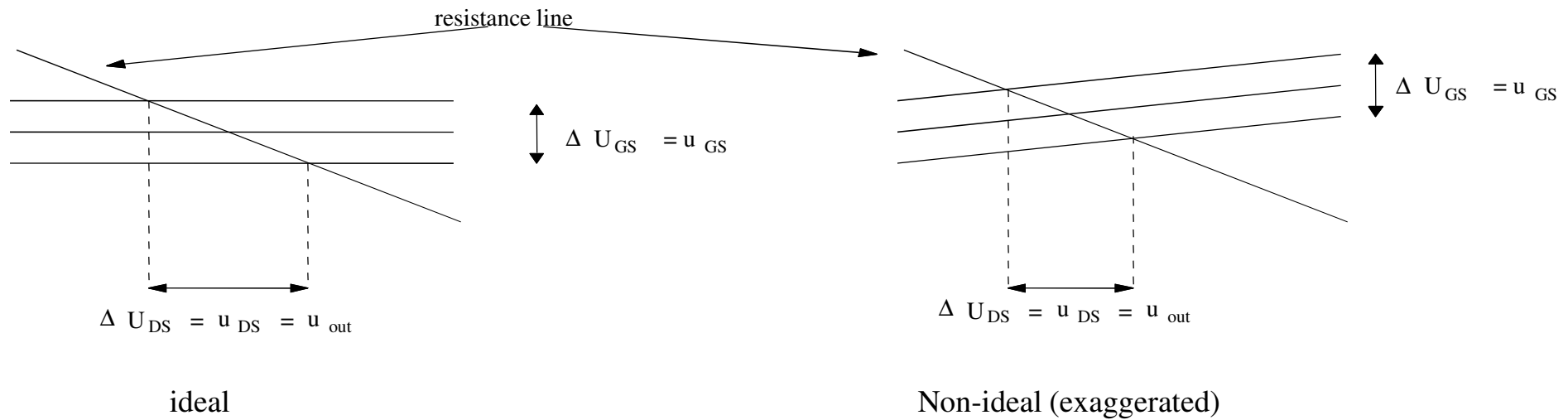
$$G = \frac{\Delta I_D}{\Delta U_{in}} = \frac{\Delta I_D}{\Delta U_{GS}}$$

$$A = \frac{\Delta U_{out}}{\Delta U_{in}} = -g_m \cdot R$$

Transition into differential  $\frac{dI_D}{dU_{GS}} = g_m$

$g_m$  is the most important parameter of MOSFET

# Small signal behaviour of the MOS transistor



## Ideal and non-ideal characteristics

$$I_D = \frac{\beta}{2} \cdot (U_{GS} - U_T)^2$$

$$\frac{dI_D}{dU_{DS}} = 0$$

$$\Rightarrow g_{DS} = 0$$

$$\Rightarrow r_{DS} = \infty$$

$$I_D = \frac{\beta}{2} \cdot (U_{GS} - U_T)^2 \cdot (1 + \lambda \cdot U_{DS})$$

$$\frac{1}{r_{DS}} = \frac{dI_D}{dU_{DS}} = \frac{1}{2} \cdot \beta \cdot (U_{GS} - U_T)^2 \cdot \lambda$$

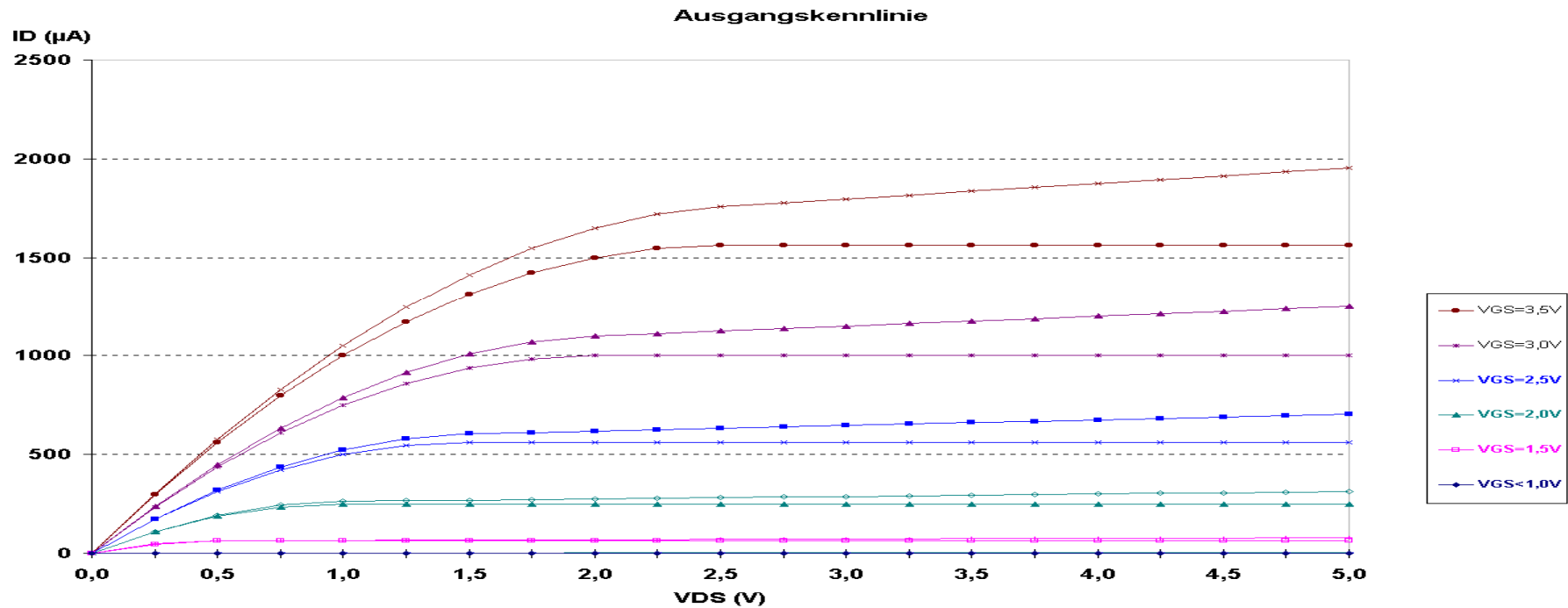
$$= I_D \cdot \frac{\lambda}{1 + \lambda \cdot U_{DS}} \approx I_D \cdot \lambda$$

$$\Rightarrow g_{DS} = I_D \cdot \lambda$$

with  $\lambda \ll$

$$\lambda \approx 0.01 - 0.05 \text{ (V}^{-1}\text{)} @ L = 10 \text{ } \mu\text{m}$$

# $G_{DS}$ depends on the operation point



$$g_{DS} = \frac{dI_D}{dV_{DS}} = \lambda \cdot I_D$$

Or more physical

$$g_{DS} = \frac{dI_D}{dV_{DS}} = \frac{k_2 \cdot I_D}{2 \cdot L_o \cdot \sqrt{U_{DS} - U_{DSS}}}$$

# Small-signal equivalent circuit



$$g_m = \frac{dI_D}{dU_{GS}}$$

$$I_D = \frac{\beta}{2} \cdot (U_{GS} - U_T)^2 \cdot (1 + \lambda \cdot U_{DS})$$

$$g_m = \beta \cdot (U_{GS} - U_T)$$

$$I_D = \frac{\beta}{2} \cdot (U_{GS} - U_T)^2$$

$$= \beta \cdot U_{GS\text{eff}}$$

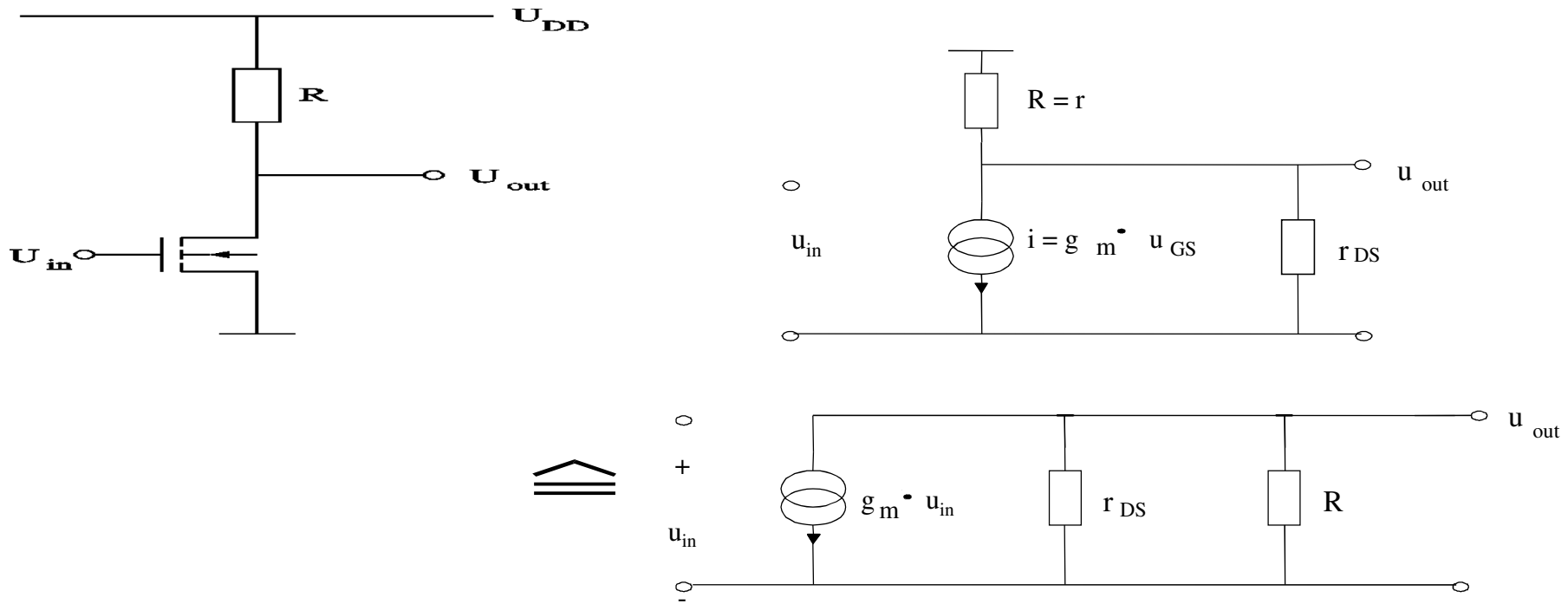
$$= \sqrt{2 \cdot I_D \cdot \beta}$$

with  $\beta = \beta_0 \cdot \frac{W}{L} = \mu \cdot \frac{\epsilon_{ox}}{t_{ox}} \cdot \frac{W}{L}$

$$g_{DS} = \frac{dI_D}{dU_{DS}}$$

$$g_{DS} = I_D \cdot \lambda = \frac{1}{r_{DS}}$$

# Small signal equivalent circuit of the inverter



$$A = \frac{\Delta U_{out}}{\Delta U_{in}} = \frac{u_{out}}{u_{in}} = \frac{-g_m \cdot u_{in} \cdot R'}{u_{in}} = -g_m \cdot R'$$

$$g_m = \beta \cdot (U_{GS} - U_T) = \sqrt{2 \cdot I_D \cdot \beta} \quad R' = (R \parallel r_{DS})$$

$$A = -g_m \cdot (R \parallel r_{DS})$$

# Example of dimensioning

Given by process:

$$\beta_0 = \mu \cdot \frac{\epsilon_{ox}}{t_{ox}} = \mu \cdot C'_{ox} = 93,2 \mu A / V^2 \quad U_{To} = 1V$$

$$\lambda = 0,02 \frac{1}{V}$$

Chosen:

$$\frac{W}{L} = \frac{50 \mu m}{5 \mu m}$$

Operation point should be:

$$U_{GS} = 2V \quad U_{DS} = 5V$$

This results in:

$$I_D = \frac{\beta}{2} \cdot (U_{GS} - U_T)^2 \cdot (1 + \lambda \cdot U_{DS}) \Rightarrow I_D \approx 510 \mu A$$

$$g_m = \beta \cdot (U_{GS} - U_T) \cdot (1 + \lambda \cdot U_{DS}) \Rightarrow g_m \approx 1000 \mu S$$

$$g_{DS} = I_D \cdot \lambda / (1 + \lambda \cdot U_{DS}) \Rightarrow g_{DS} = 9,3 \mu S$$

$$r_{DS} = 110 k \Omega$$



# Gain of an inverter with resistive load:

$$R = 10 \text{ k} \Omega \quad r_{DS} \parallel R = 9,2 \text{ k} \Omega$$

$$\begin{aligned} A &= -g_m \cdot (r_{DS} \parallel R) \\ &= -1000 \mu\text{S} \cdot 9,2 \text{ k} \Omega \\ &= -9,2 \end{aligned}$$

If the amplifier is „open“ ( $R=\infty$ ), the result is:

$$A = -g_m \cdot r_{DS} = -1000 \mu\text{S} \cdot 110 \text{ k} \Omega = -110$$

## Internal gain of a transistor

$$\begin{aligned} R \gg r_{DS} &\Rightarrow A \approx -g_m \cdot r_{DS} \\ &= -\frac{\sqrt{2 \cdot I_D \cdot \beta}}{\lambda \cdot I_D} \end{aligned}$$

$$A \propto -\frac{1}{\sqrt{I_D}}$$

Dependent of operation point

A large-signal parameter which determines the small signal behaviors

## Specifics of analog integrated circuit

*(compared to discrete circuit)*

- Limited isolation / limited interconnectivity due to many parasitic pn-transitions
- Large variation/scattering of component parameters (e.g.:  $V_t: \pm 100\text{mV}$ ,  $R: \pm 20\%$ )
- Limited choice of components and non-ideal components
- Matching of scattering and isotherme
- Highly developed models
- Large complex circuit possible

## Example of a tolerance calculation

Gain of an inverter

$$\begin{aligned} A &\approx g_m \cdot R \approx \beta \cdot (V_{GS} - V_T) \cdot R \\ &= \frac{W}{L} \mu_n \cdot \frac{\varepsilon_{OX}}{t_{OX}} \cdot (V_{GS} - V_T) \cdot R \end{aligned}$$

Scattering of processes:

R:  $\pm 15\%$

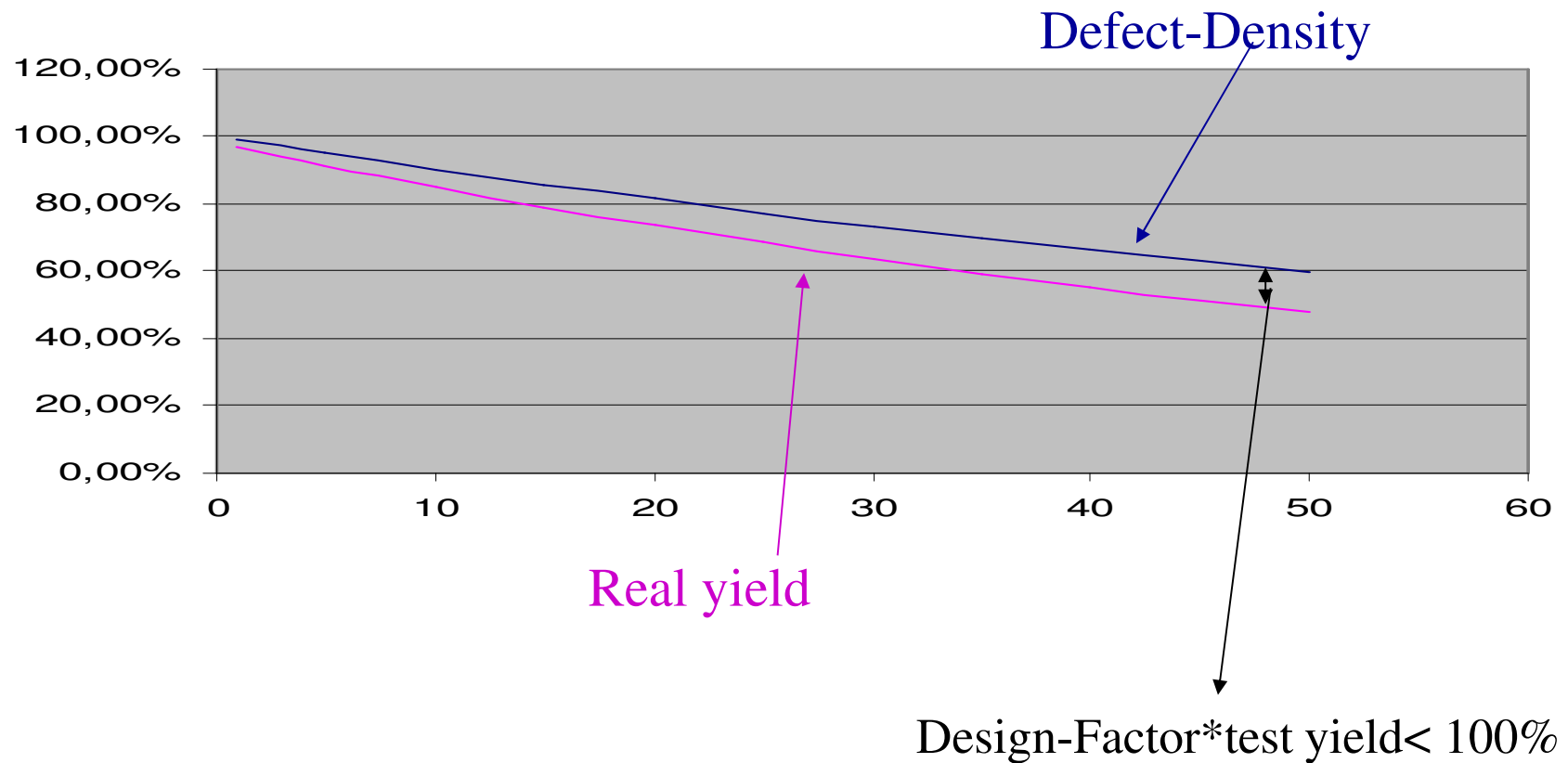
Vt:  $\pm 100 \text{ mV}$   $\Rightarrow \pm 10\%$  bei  $V_{GSE} = 1 \text{ V}$

Tox:  $\pm 10\%$

O v e r a l l S c a t t e r i n g

$$= \sqrt{15\%^2 + 10\%^2 + 10\%^2} > \pm 20\%$$

## Yield in dependance on chip area



Yield decreases exponentially with chip area

Real yield is reduced by the design-factor and the test yield.

## Method for robust design

(insensitive for sattering and allowing so high design-factor)

1. Usage of matching devices for example :
  - Divider (resistor, capacity, MOS)
  - Current mirror/ current source
2. Usage of larger structures and symmetric layout for critical functions
2. Bandgap voltage reference
3. Regelung instead Steuerung
4. Difference amplifier